







00. CONTENT

INDEX

01. SAFETY INSTRUCTIONS STANDARDS TO FOLLOW	18
02. OPERATOR	
TECHNICAL SPECIFICATIONS	4A
DIMENSIONS	4B
COMPONENT KIT	4B
03. INSTALLATION	
INSTALLATION MAP	5
UNLOCK OPERATOR	5 6A
FOUNDATION	6B
OPERATOR INSTALLATION	
INSTALLATION OF STEEL GEAR RACK	8
INSTALLATION OF PLATES THE LIMIT SWITCHES	9
0	
04. MAINTENANCE	
MAINTENANCE	10
05. ELECTRONICS	
ELECTRONICS ACCESS	11A
GENERAL INFORMATION	11B
FREQUENCY CONVERTER	12A
CONECTORS	12B
OF CONNECTIONS SCHEME	
O6. CONNECTIONS SCHEME FREQUENCY CONVERTER CONNECTION	12
MR13 RECEIVER CONNECTION	13
ACCESSORY CONNECTION	
ACCESSORT CONNECTION	15
07. PROGRAMMATION	
DIGITAL NUMERIC KEYBOARD	16A
MENU NAVIGATION	16B
LOCK/UNLOCK KEYBOARD	17A
MENU 04 ACCESS	17B
MENU 04	18A
LED DISPLAY MESSAGES	19A
FINAL CONSUMERS/SPECIALIZED TECHNICIANS INSTRUCTIONS	19B
PERFORMANCE TEST	20A
MR13 RECEIVER	21A
MX13 TRANSMITTER (OPCIONAL)	21B

01. SAFETY INSTRUCTIONS

STANDARDS TO FOLLOW

This product is certified in accordance with European Community (EC) safety standards.

This product complies with Directive 2011/65/EU of the European Parliament and of the Council, of 8 June 2011, on the restriction of the use of certain hazardous substances in electrical and electronic equipment.

(Applicable in countries with recycling systems).

This marking on the product or literature indicates that the product and electronic accessories (eg. Charger, USB cable, electronic material, controls, etc.) should not be disposed of as other household waste at the end of its useful life. To avoid possible harm to the environment or human health resulting from the uncontrolled disposal of waste, separate these items from other types of waste and recycle them responsibly to promote the sustainable reuse of material resources. Home users should contact the dealer where they purchased this product or the National Environment Agency for details on where and how they can take these items for environmentally safe recycling. Business users should contact their vendor and check the terms and conditions of the purchase agreement. This product and its electronic accessories should not be mixed with other commercial waste.



This marking indicates that the product and electronic accessories (eg. charger, USB cable, electronic material, controls, etc.) are susceptible to electric shock by direct or indirect contact with electricity. Be cautious when handling the product and observe all safety procedures in this manual.

01. SAFETY INSTRUCTIONS

GENERAL WARNINGS

- •This manual contains very important safety and usage information. very important. Read all instructions carefully before beginning the installation/usage procedures and keep this manual in a safe place that it can be consulted whenever necessary.
- This product is intended for use only as described in this manual. Any other enforcement or operation that is not mentioned is expressly prohibited, as it may damage the product and put people at risk causing serious injuries.
- This manual is intended firstly for specialized technicians, and does not invalidate the user's responsibility to read the "User Norms" section in order to ensure the correct functioning of the product.
- •The installation and repair of this product may be done by qualified and specialized technicians, to assure every procedure are carried out in accordance with applicable rules and norms. Nonprofessional and inexperienced users are expressly prohibited of taking any action, unless explicitly requested by specialized technicians to do so.
- Installations must be frequently inspected for unbalance and the wear signals of the cables, springs, hinges, wheels, supports and other mechanical assembly parts.
- Do not use the product if it is necessary repair or adjustment is required.
- · When performing maintenance, cleaning and replacement of parts, the product must be disconnected from power supply. Also including any operation that requires opening the product cover.
- •The use, cleaning and maintenance of this product may be carried out by any persons aged eight years old and over and persons whose physical, sensorial or mental capacities are lower, or by persons without any knowledge of the product, provided that these are supervision and instructions given by persons with experienced in terms of usage of the product in a safe manner and who understands the risks and dangers involved.

• Children shouldn't play with the product or opening devices to avoid the motorized door or gate from being triggered involuntarily.

WARNINGS FOR TECHNICIANS

- Before beginning the installation procedures, make sure that you have all the devices and materials necessary to complete the installation of the product.
- You should note your Protection Index (IP) and operating temperature to ensure that is suitable for the installation site.
- Provide the manual of the product to the user and let them know how to handle it in an emergency.
- If the automatism is installed on a gate with a pedestrian door, a door locking mechanism must be installed while the gate is in motion.
- Do not install the product "upside down" or supported by elements do not support its weight. If necessary, add brackets at strategic points to ensure the safety of the automatism.
- Do not install the product in explosive site.
- Safety devices must protect the possible crushing, cutting, transport and danger areas of the motorized door or gate.
- · Verify that the elements to be automated (gates, door, windows, blinds, etc.) are in perfect function, aligned and level. Also verify if the necessary mechanical stops are in the appropriate places.
- The central must be installed on a safe place of any fluid (rain, moisture, etc.), dust and pests.
- You must route the various electrical cables through protective tubes, to protect them against mechanical exertions, essentially on the power supply cable. Please note that all the cables must enter the central from the bottom.
- If the automatism is to be installed at a height of more than 2,5m from the ground or other level of access, the minimum safety and health requirements for the use of work equipment workers at the work of Directive 2009/104/CE of European Parliament and of the Council of 16

01. SAFETY INSTRUCTIONS

September 2009.

- Attach the permanent label for the manual release as close as possible to the release mechanism.
- Disconnect means, such as a switch or circuit breaker on the electrical panel, must be provided on the product's fixed power supply leads in accordance with the installation rules.
- If the product to be installed requires power supply of 230Vac or 110Vac, ensure that connection is to an electrical panel with ground connection.
- •The product is only powered by low voltage satefy with central (only at 24V motors)

WARNINGS FOR USERS

- Keep this manual in a safe place to be consulted whenever necessary.
- If the product has contact with fluids without being prepared, it must immediately disconnect from the power supply to avoid short circuits, and consult a specialized technician.
- Ensure that technician has provided you the product manual and informed you how to handle the product in an emergency.
- If the system requires any repair or modification, unlock the automatism, turn off the power and do not use it until all safety conditions have been met.
- In the event of tripping of circuits breakers of fuse failure, locate the malfunction and solve it before resetting the circuit breaker or replacing the fuse. If the malfunction is not repairable by consult this manual, contact a technician.
- Keep the operation area of the motorized gate free while the gate in in motion, and do not create strength to the gate movement.
- Do not perform any operation on mechanical elements or hinges if the product is in motion.

RESPONSABILITY

- · Supplier disclaims any liability if:
 - Product failure or deformation result from improper installation use or maintenance!
 - Safety norms are not followed in the installation, use and maintenance of the product.
 - Instructions in this manual are not followed.
 - Damaged is caused by unauthorized modifications
 - In these cases, the warranty is voided.

SYMBOLS LEGEND



 Important safety notices



Useful information



Programming information



Potentiometer information



 Connectors information



Buttons information

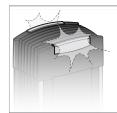
02. OPERATOR

TECHNICAL SPECIFICATIONS



Stark is designed to automate high weight sliding gates(max 8000kg) and is provided with a control board with frequency inverter, allowing better management and control over the operator.

To identify the different phases of operation, STARK is provided with two LED RGB:



By opening course:

Flashing light turn flashing GREEN light

By the pause time while open: Flashing light turn BLUE light

By closing course:

Flashing light turn flashing RED light

General advantages of operator:

- Opening and closing speed control as well as opening and closing deceleration speed
- Partial opening
- Presentman
- Flashing light output
- · Photocell and safety band inputs
- Emergency stop
- · Acceleration and deceleration ramp control
- Automatic closing

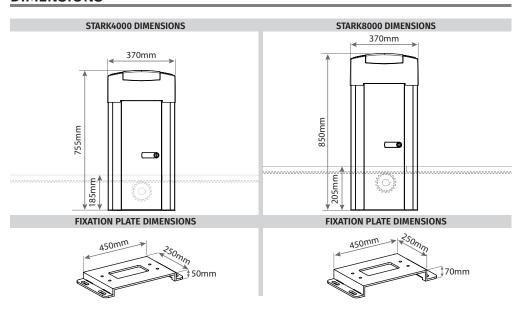
Operator technical specifications:

	STARK4000	STARK8000
• Power Supply	230Vac/50Hz	230Vac/50Hz
• Power	750W	1500W
• Current	4A	8A
Working temperature	-20°C a +70°C	-20°C a +70°C
• Speed	0.18m/s	0.12m/s
Maximum weight of gate	4000 kg	8000 kg
• IP Protection	IP54	IP54
• Force (50Hz frequency)	115 Nm	290 Nm
Maximum force applied to gate	450kg	600kg
Working frequency	75%	75%
Accessory power supply	24Vdc/200mA	24Vdc/200mA

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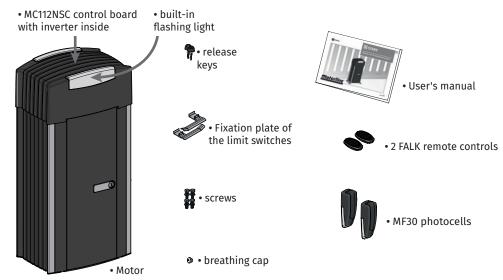
02. OPERATOR

DIMENSIONS

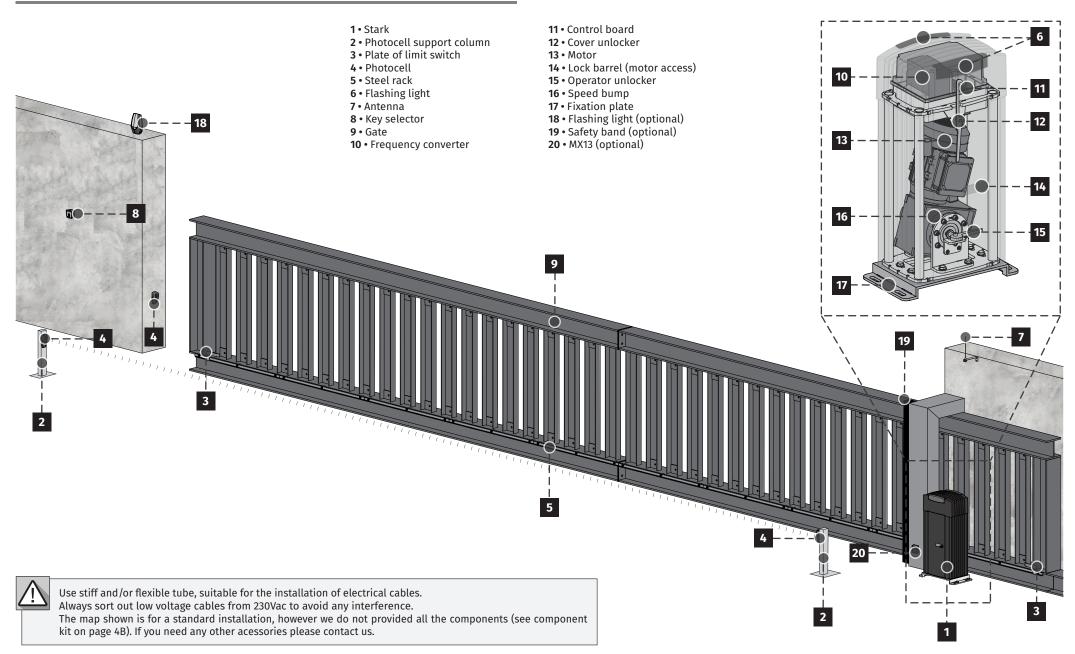


COMPONENT KIT

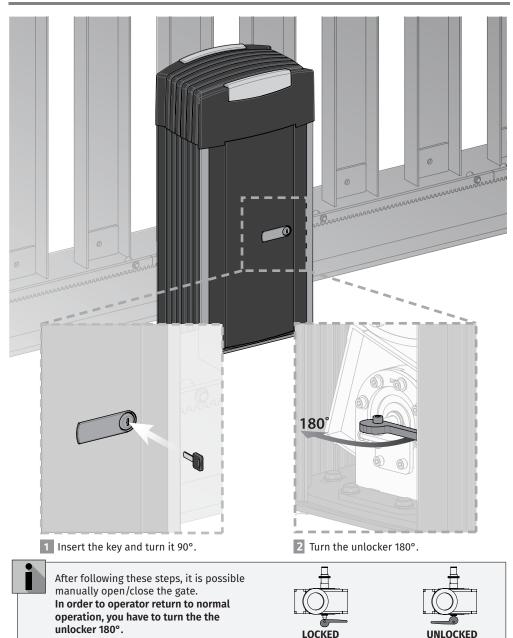
You should check if the following items are in the operator kit before you start the installation.



INSTALLATION MAP

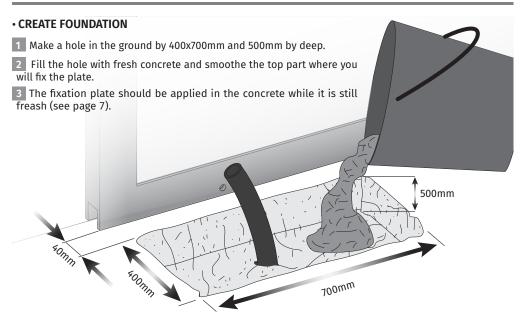


UNLOCK OPERATOR



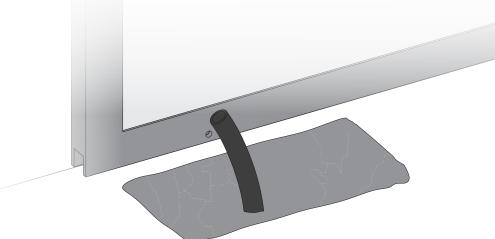
03. INSTALLATION

FOUNDATION



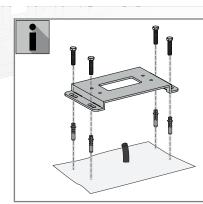
EXISTING FOUNDATION

In case there is already a foundation,proceed the installation (see page 7).



OPERATOR INSTALLATION





EXISTING FOUNDATION

*In case you are installing the motor on an existing foundation. fix the plate on the foundation in concrete, fasten the suitable screws and steel anchors (not supplied in the kit).



Be careful with the importance of this installation, as it will be exposed to motions of heavy loads.

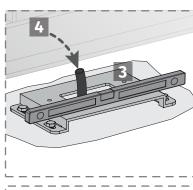
The screws and steel anchors must be appropriate to the floor and weight of the gate.

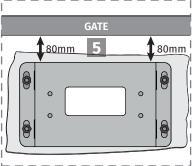
- 1 Place the screws and steel anchors into the four holes of the fixation plate and tighten.
- 2 With the concrete still fresh, apply the fixation plate.

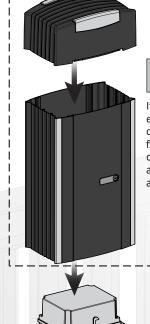
*In case you are installing the motor on an existing foundation, fix the plate on the foundation in concrete, fasten the suitable screws and steel anchors (not supplied in the kit).

NOTE • It is important to leave one or more tubes to run electrical cables through the fixation plate.

- 3 With a level, verify if the fixation plate is levelit horizontally. The fixation plate should be placed parallel to the gate to ensure that the steel rack and pinion fit perfectly.
- 4 Cross the eletrical cables to connect the motor to the acessories and power supply. Leave the cables with a length that ensure easy connection to the control board.
- 5 Adjust the distance between the fixation plate and the gate. The recommended distance is 80mm, considering that the screws are centered with the fixation plate holes, allowing adjustment (if necessary).
- 6 Place the motor in the fixation plate, leaving it centered and tighten the screws.
- 7 Replace the screw for the breathing cap of the speed bump (supplied on the kit).









If it is necessary to easy the installation of the motor to the fixation plate, you can remove the aluminum profiles as illustrated here.



INSTALLATION OF STEEL GEAR RACK



Put the gate open and unlock the motor (page 6A). Fix the steel rack with suitable supports for installation.

1 Place a piece of rack on top of the pinion and fix it to the gate.

NOTE • Level it horizontally with a leve, before fixing.

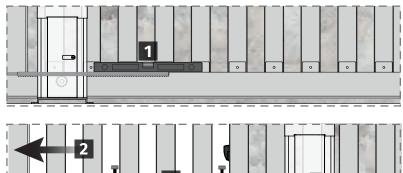
- 2 Close the gate a bit until it is possible to apply another piece of rack on the pinion, and fix it to the gate.
- 3 To synchronize the teeth with the piece already installed, use na additional piece of rack (A) and place it under the union of the other two, holding them with clamps (B).
- 4 Open the gate to support the point of the new piece of rack on top of the pinion and weld the spacer.
- 5 Remove the piece of auxiliary rack and open the gate until the other end of the rack stands on top of the pinion. Weld the spacer.
- 6 Repeat the previous steps for each meter of the rack you need install.
- 7 Manually, test the movement of the gate with all racks installed and in case of finding some friction between the rack and pinion, adjust the rack.

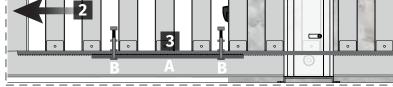


During the course of the gate, all elements of the rack must be mesh properly with the pinion!

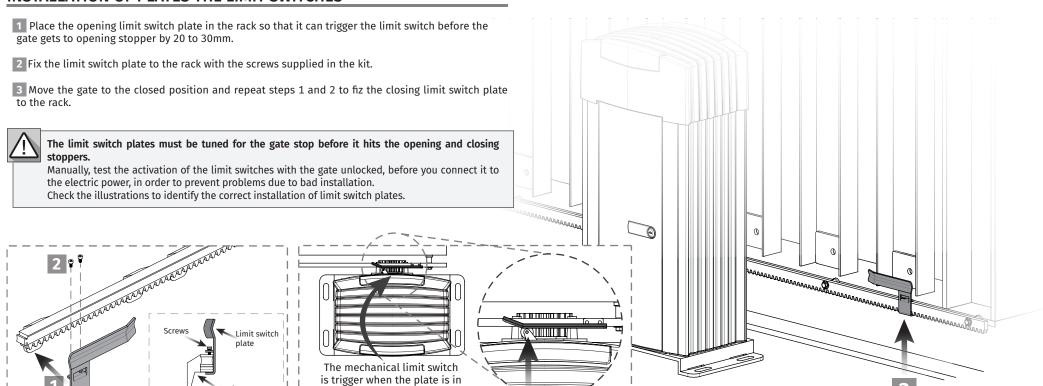
Do not welded the spacers to the rack!

Do not use mass or other types of lubrificant between rack and pinion, because can damage the operator!

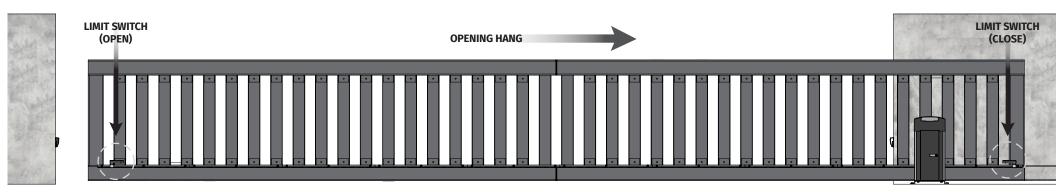




INSTALLATION OF PLATES THE LIMIT SWITCHES



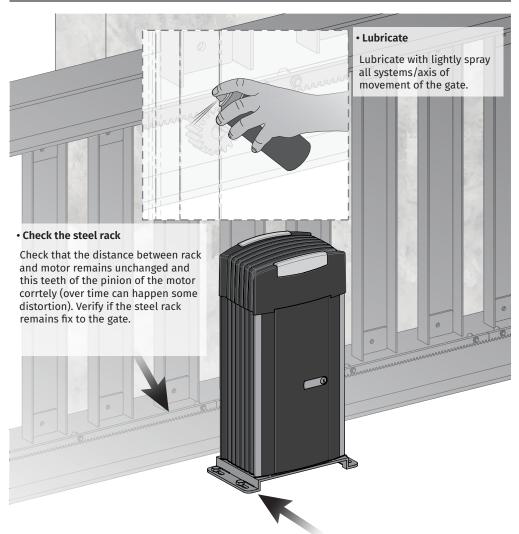
contract with the spring.





04. MAINTENANCE

MAINTENANCE



• Check the support plate

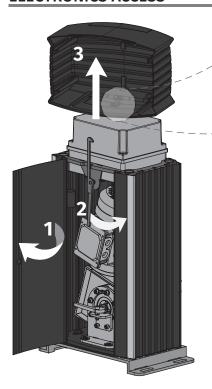
Check all supports remains fix to the pillars and gate for the good functioning of the operator.



The maintenance measures must be made every 6 monthns to maintain the good functioning of the operator.

05. ELECTRONICS

ELECTRONICS ACCESS



1 · Open door

Insert the key and open the door (page 6A).

2 • Turn cover brake

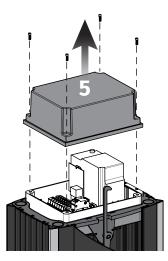
Turn the cover brake to the right side (if you are in front to the motor).

3 · Lift up the cover

Lift up the cover with caution.

4 · Desconnect power supply

Desconnect the cable that connects the control board to LEDs, so you can put down the cover.



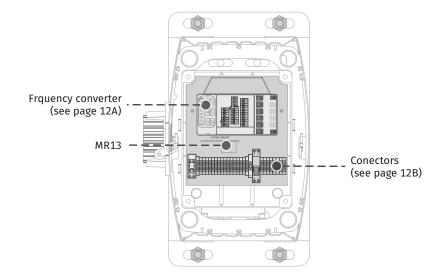
5 • Remove electronic cover

Unscrew the 4 screws and remove the electronic components protection cover. The process is now complete.

05. ELECTRONICS

GENERAL INFORMATION

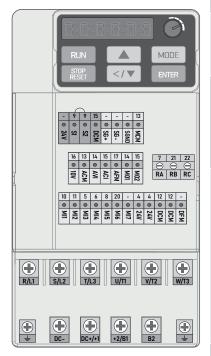
- STARK 4000 and 8000 are provided with MC112NSC control board capable of function with motors until
- It owns a frequency converter to perform smooth starts and stops, which makes the product reliable and longer durability.
- The opening/closing speed can be adjusted and also deceleration speed.
- The display built-in contro board allows an cognitive navigation through the menus and parameters, also an easy configuration.
- It is possible to see the measure of cycles made by the gate (opening and closing course complete means 1 cycle).
- The control board is capable of receiving ROLLING CODE remote controls signal through the MR13 receiver, as well as connecting obstacle detection kits throught the MX13 transmitter.



05. ELECTRONICS

FREQUENCY CONVERTER

In the following panel are all inputs and outputs of the fresquency converter.



24V · STOP Common

S1 · STOP Button

S2 · STOP Button

DCM • Without use

SG+ • Without use

SG- • Without use

SGND • Without use

MCM · Voltage input for outputs M01

10V · Without use

ACM • Without use

AVI · Without use

ACI • Without use

AFM • Without use

M01 · Pulse output for MR13 and LED light control

MI1 · Opening Button (sequential)

MI2 · Close Button/pedestrian

MI3 · Open limit switch

MI4 · Close limit switch

MI5 · Photocells

MI6 · Safety band

MI7 · Encoder input

24V · Photocell and Radar output (24Vdc 3W)

24V · Photocell and Radar output (24Vdc 3W)

DCM • 24Vdc 3W Negative

DCM • 24Vdc 3W Negative

DFM • Without use

RA · NO Relay output for flashing light

RB • Without use

RC · Relay Common for flashing light

R/L1 · Power Supply 230Vac

S/L2 • Power Supply 230Vac

U/T1 · Motor output - Phase 1

V/T2 • Motor output - Phase 2

W/T3 · Motor output - Phase 3

T/L3 · Without use

DC- · Without use

DC+/+1 · Without use

+2/B1 · Braking Resistor Wire

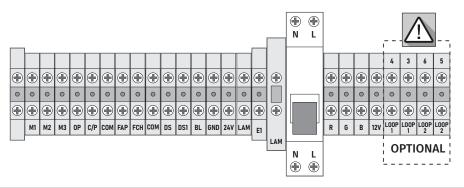
B2 • Braking Resistor Wire

• Ground wire

05. ELECTRONICS

CONETORES

In the following panel are all inputs and outputs of connectors.



E1 · Ground

M1 · Motor output - Phase 1

M2 · Motor output - Phase 2

M3 · Motor output - Phase 3

OP · Opening Button (sequential)

C/P · Close Button/pedestrian

COM • Commom input (limit switch or start)

FAP · Open limit switch

FCH · Close limit switch

COM • Commom input (limit switch or start)

DS • Photocells input

DS1 · Safety band input

BL • STOP/Push button input

GND • 24Vdc Negative

24V · Photocell and Radar output (24Vdc 3W)

LAM • Fuse output for flashing light (fuse 2A 500W, 230V)

LAM · Neutral

E1 · Ground

N · Power Supply 230Vac

L • Power Supply 230Vac

Circuit breaker DPN 16A

R · Red LED output

G · Green LED output

B • Blue LED output

12V · Power Supply 12Vdc 2W LED

LOOP1 · LOOP1 Magnetic loop

LOOP1 · LOOP1 Magnetic loop

LOOP2 · LOOP2 Magnetic loop

LOOP2 · LOOP2 Magnetic loop

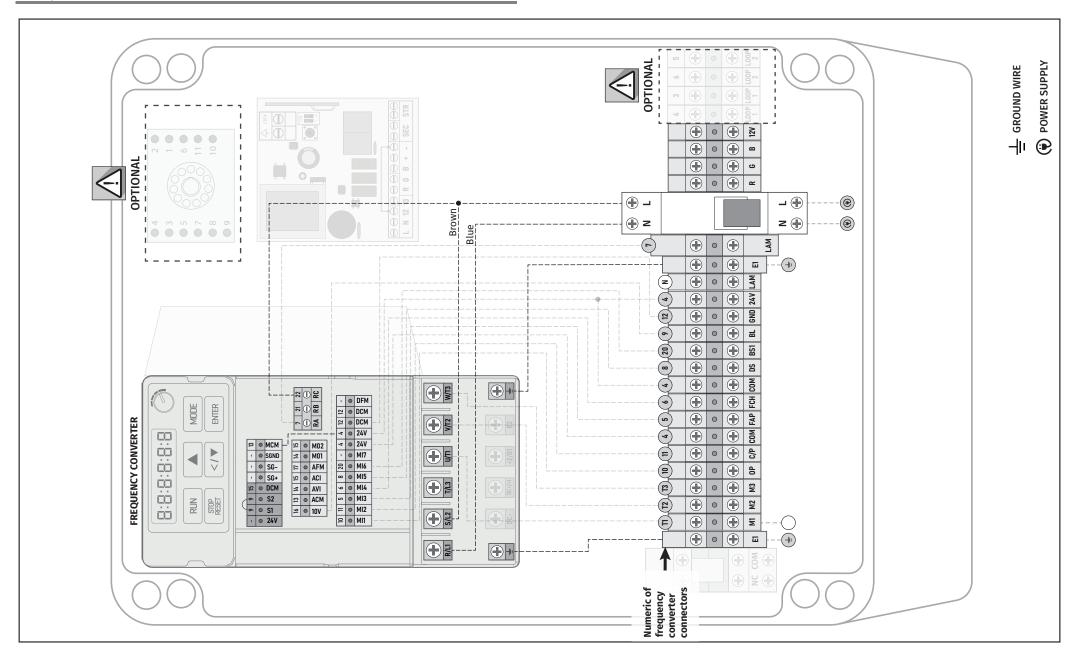


OPTIONAL



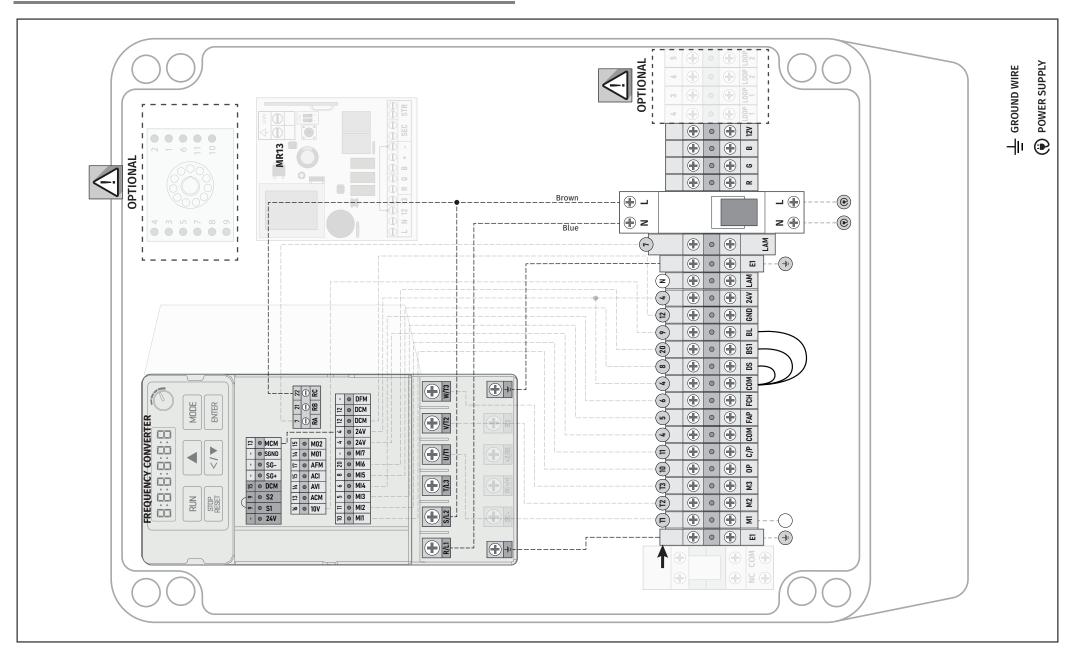
06. CONNECTIONS SCHEME

FREQUENCY CONVERTER CONNECTION



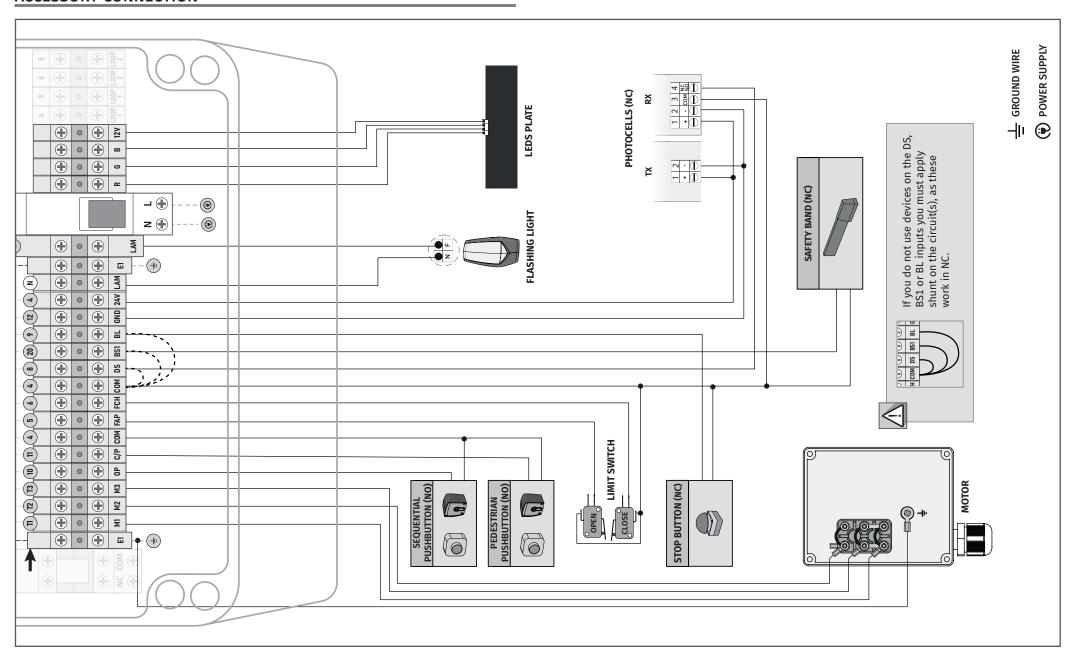
06. CONNECTIONS SCHEME

MR13 RECEIVER CONNECTION

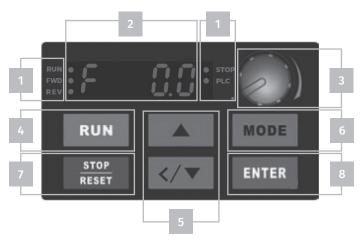


06. CONNECTIONS SCHEME

ACCESSORY CONNECTION



DIGITAL NUMERIC KEYBOARD



	RUN	Converter OK	
	FWD	Climbing motion	
1	Status Display	REV	Climbdown motion
1 Displays the current status of control board	STOP FLASHING	Stand by	
	Bourd	STOP OFF	Enable STOP or gate in motion
		PLC	The operator is function
	LED Dienley		

- LED Display
 Indicates frequency, voltage, current, user-defined units, etc
- 5 UP and DOWN Arrows
 Allow define the number of parameters and change the numeric data for main frequency
- 6 MODE
 Change in different views
- 7 STOP/RESET
 Restarts the device after a failure occurs
- 8 Used to enter/change programming parameters



- 3 and 4 cannot be perform.
- Only the menus on page 18A e 18B can be set by the user. Any other changes made to a menu than those listed on pages 18A e 18B will void the warranty. Motorline is not liable for damage if this indication is not respected.

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07. PROGRAMMATION

MENU NAVIGATION





1 Press ENTER to access to MENU.



2 Use the arrows, and select one of the **SUBMENUS**.



Press ENTER to access to SUBMENU.



4) Use the arrows, to change the value.



Press ENTER to confirm.



6 End indicates success. Err indicates error.



To exit of the MENU press "MODE" until you reach "C".



LOCK/UNLOCK KEYBOARD

The keypad lock is done by password. Below are the steps for setting and using the password.





SET PASSWORD

Enter parameter **00.08** and write a password to lock the keyboard.

Parameter value will be change from 0 (disable) to 1 (enable).



CHANGE OF PARAMETER

- **1** Enter parameter **00.07** and write the set password. This will temporarily unlock the keyboard.
- **2** · Change the parameter you desire. The unlock will remain until the motor made a new operation.



WRONG PASSWORD

1 · Have 3 attempts to write the correct password in parameter 00.07.

LED Display indicates the number of failed attempts from 01 to 03.

Example: At the 1st wrong attempt appears on LED Display 01.

- 2 · At 4th wrong attempt, the LED Display will display a error message Pcode.
- 3 · Unplug the power supply to have another 3 attempts.



RESET FACTORY SETTINGS

- 1. Write on parameter 00.07 the code 9999 two times.
- 2 · After press ENTER Button for 10 seconds.

The factory value will be reset.



DISABLE PASSWORD

- 1 · Enter parameter 00.07 and write the set password.
- 2 · Enter parameter 00.08 and change the value from 1 to 0. Password will be disable.



See the page 16B to menu navigation.

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07. PROGRAMMATION

MENU 04 ACCESS





1 Press **MODE** until reach the function **H**.



2) Press ENTER to access the function H.



3 Use the arrows to find value **04**.



4) Press ENTER to access 04.



See the page 16B to menu navigation.

MENU 04



If the values are incorrectly adjusted, there is a risk of damage to the motor and inverter.

Parameter	Function	Settings	Factory Setting
04.00	OPEN SPEED Allows set gate opening speed.	00.00 to 60.00 Hz	50.00 Hz
04.01	CLOSE SPEED Allows set gate closing speed.	00.00 to 60.00 Hz	50.00 Hz
04.02	OPENING DECELERATION SPEED Allows to select the rate of deceleration on climbing. NOTE • The changes on deceleration opening or closing speed will change the lenght deceleration.	00.00 to 40.00 Hz	25.00 Hz
04.03	CLOSING DECELERATION SPEED Allows to select the rate of deceleration on climbdown. NOTE • If change the gate speed it is necessary adjust this parameter.	00.00 to 40.00 Hz	25.00 Hz
04.50	LENGHT OPENING DECELERATION Allows to set the lenght of deceleration. The lenght can be set in course programming or in the menu diretly. NOTE • At 1000 it means 1.5 meters of deceleration. If select 500 means a deceleration of 750mm.	0 to 1000 (ex: 1000=1.5m)	150 (250mm)
04.51	LENGHT CLOSING DECELERATION Allows to set the lenght of deceleration. The lenght can be set in course programming or in the menu diretly. NOTE • At 1000 it means 1.5 meters of deceleration. If select 500 means a deceleration of 750mm.	0 to 1000 (ex: 100=1.5m)	150 (250mm)
04.52	PAUSE TIME Allow to set the time the gate is paused when it is open. NOTE • By set 0 seconds, the gate has no pause time.	0 = OFF 0 to 99 (ex: 99=99 sec.)	0
04.53	PRESENTMAN This menu allows the gate to be pushed open until the limit switch is reached. In order to close the gate the user must be permanently pressing the gate down button. In this function the pedestrian button will be climbdown.	0 = Disabled 1 = ON	0 = Disabled
04.54	OPERATING LOGIC This menu allows to add 3 working modes each with their specifications.	0 = Step by step 1 = Condominium 2 = Inversion	0 = Step by step
04.55	ACCELERATION RAMP AT OPENING This menu allows you to adjust the opening acceleration ramp time to allow a smoother start of the gate.	0 a 200 (ex: 100=1 sec.)	150 (1.5 sec.)
04.56	ACCELERATION RAMP AT CLOSING This menu allows you to adjust the closing acceleration ramp time to allow a smoother start of the gate.	0 a 200 (ex: 100=1 sec.)	150 (1.5 s)

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07. PROGRAMMATION

MENU 04

Parameter	Function	Settings	Factory Setting
04.57	PEDESTRIAN OPENING TIME This menu can select the lenght of the pedestrian opening. Knowing that 100 means 8M if put 12 means opening of a meter. If the present man is active this menu doesn't work. If set to 0 the CH/PED button will only be closed.	0 to 100	15 = 1.5 m
04.58	DECELERATION RAMP AT INVERSION Allows to set the deceleration time at inversion. Steeper or smoother stop.	0 to 200 (ex: 100=1 sec.)	100 (1 s)
04.59 04.60	HANDLING COUNT This function allows to view all complete handling performed by the operator. The menu 04.60 show the number of handling performed to the thousands while the menu 04.59 show up to hundreds of thousands (see example).	and clos Example: Menu 04.59	ing = 1 opening ing cycle. Menu 04.60
04.61	FLASHING LIGHT OUTPUT Allows to change the logic of flashing light. If it is set to 0 the flashing light will be active only when the motor is working. If select 1 the flashing light is active as long as it exits the closing limit switch, when it reaches the closing limit switch it will remain light for the time set in menu 04.63.	0 = plugged in opening and closing 1 = courtesy light	0 = opening and closing
04.62	RESET HANDLING COUNT This menu allows to reset the handling of menus 04.59 and 04.60. In order to be able to reset, will need to enter the password available only to the Motorline technical department.	Password must be entered	
04.63	COURTESY LIGHT TIME This menu allows adjust the time when the light is on, since reaching the limit switch if selected in menu 04.61.	0 to 50 Min	3 = Min
04.64	PROGRAMMATION MENU This menu has the function of placing the control board in course programming.	0 to 1	1 = control board in programming
06.07	OVER FORCE DETECTION LEVEL 11 to 250% (100% menas to the nominal current of the inverter)	10% to 250%	120
06.08	WAITING TIME WITH OVER FORCE Allow to set how long it will take to react to over force.	00 to 60ms	0.1ms



18B

LED DISPLAY MESSAGES

Message displayed	Description	
F 8 0.0 FF	Displays the master frequency of the CA converter.	
PROPERTY HE SOLD STOP SPEC	Displays the effective output frequency at terminals U/T1, V/T2, and W/T3.	
REVE R S.O SEC	Displays output current at terminals U/T1, V/T2, and W/T3.	
From Frd Stor	Open Gate - Displays the open operating status on the CA converter.	
RUN* PRO* REY* FE u *STOP *PLC*	Close Gate - Displays the close operating status on the CA converter.	
c 00	Input info. This info is displayed whenever there is no common input or parameter PLC1 is set to PLC0. It may also happen a short circuit in the 24V	
REV. PL . STOP	Mandatory mode for operation (do not change this menu)	
RUN EF	External failure.	
₩ End	Shows "End" for approximately 1 second if the input was accepted, while press Enter After set a value parameter, the new value is automatically add to the memory. To change an entry use the arrows and	
RUN Err	Displays "Err" if the entry is wrong.	
EV. Sto	STOP active the crank sensor.	
C333	Nothing active.	
C888	Photocells active.	
C101	Open limit switch active.	
C202	Close limit switch active.	

07. PROGRAMMATION

FINAL CONSUMERS/SPECIALIZED TECHNICIANS INSTRUCTIONS

Failure info	Failure description	Solutions
ОC	OVERCURRENT Abnormal current increase	 01 • Check that the motor power correponds with the output power of the AC motor converter. 02 • Check for possible short circuits on wire connections of U/T1, V/T2, W/T3. 03 • Check for possible short circuits on wire connections between AC motor converter, motor and ground wire. 04 • Check for loose contacts between the AC motor converter and motor. 05 • Check for possible excessive load conditions on the motor. 06 • After a short circuit, if exist any malfunctions of the AC motor converter, you should send the product for the manufacturer.
00	OVERVOLTAGE The DC voltage exceeded the maximum allowed value.	 01 • Check if the input voltage of AC motor converter is within the rated voltage class. 02 • Check for possible voltage deviations. 03 • Check that the power required for the brake is within the set limits.
Lu	LOW VOLTAGE AC motor converter detects DC terminal voltage is lower than the minimum value.	O1 • Check if the input voltage of AC motor converter is within the rated voltage class. O2 • Check for abnormal motor load. O3 • Check for the incoming power wires are correct with R-S-T (for three-phase models) without phase be lost.
οL	OVERLOAD AC converter detects exceed current on output control.	O1 • Check if the motor is overload. O2 • Use the following model, with AC converter motor power.
oc R	OVERLOAD DURING ACCELERATION	 01 • Short circuit on motor output, check if the insulation on the output lines is in good conditions. 02 • Acceleration time too short: Increase the acceleration time.
ocd	OVERCURRENT DURING DECELERATION	01 • Short circuit on motor output, check if the insulation on the output lines is in good conditions.
ot¦	DETECTION OF EFFORT AND OVER COMSUMPTION	01 • Check parameter 06.04 and set lower sensibility (set a value near to 200%).02 • Check if the gate is stuck at some point.



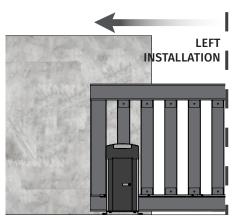


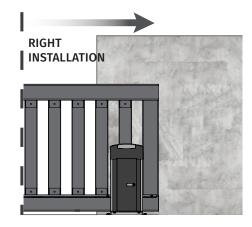
PERFORMANCE TEST

After installation of the control board and wiring, ensure that all connected components are working properly. To do this, follow the steps:

LIMIT SWITCHES TEST

First, you must set whether the operator is installed to the right or left of the gate. This information will indicate which side of opening and closing.



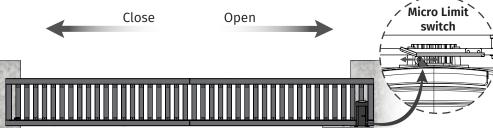


This test will be exemplified with the operator installed on the right side.

Tilt the spring operator limit switch to the right until you hear a "click" sound.

The display should show "C101"! Now tilt the spring limit switch to the left until you hear a "click" sound and show on the display "C202". If the "C202" appears first, you must change the cables.

Attention: When change the cables you must also change the limit switches cables and the motor wire to reverse the direction of motion.





Limit switches are an important motor safety system. It is of utmost importance that they are correctly connected to the control board, otherwise they may cause serious damage or injuries.

Motorline®

07. PROGRAMMATION

PERFORMANCE TEST

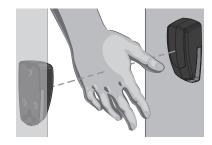
PHOTOCELLS TEST

The photocells are a safety device that inform the control board that any object is obstructing the gate path. They send a signal so that the gate does not close preventing damage to this object.

The photocells are connected to the DS input of the control board (see page 15). This input has an assigned LED that informs us of the photocell connection status. This LED is always on when a safety device is connected (NC).

To test the connection of the photocells in the control board, simply interrupt the signal between the two photocells by placing your hand in front of one of them. A "click" sound will indicate that the signal has been interrupted and will show on the display "C888" while the photocells are interrupted.

If it does not work this way, there is a problem connection between the photocells and the control board.



COURSE PROGRAMMING

NOTE · It is not possible to deceleration more than 1.5 meters.

- 1. Put the door (manually) in the closed position.
- 2 · Access menu 04.64 and set 1.
- 3 · Press **OP** button or press the remote control programmed in **MR13**.
- 4 · The gate will start to open.
- **5** When you want to start deceleration on opening, press again on remote controlor the **OP** button. The gate will slow down.
- 6 · When the gate reaches the opening limit switch, it will start closing.
- **7** · When you want to start closing deceleration, press again on remote controlor the OP button. The gate will slow down.
- 8 · When the gate reaches the closing limit switch, the course programming is completed.

MR13 RECEIVER

Wireless receiver for receiving signal from ROLLING CODE Motorline remote controls and MX13 transmitter for safety circuits (eg safety bands, magnetic contacts).

This receiver allows the use of a single MX13 transmitter.



DIPPER

• Dippers 1 and 2 allow you to set the time interval between signal sends.

This signal shows the proper functioning of the sender's communication with the receiver.









Function off

Level 3

Level 1



• For MX13 and MR13 devices to be synchronized, you must configure dippers 1 and 2 in the same way on both devices.



LEARN KEY

• This button is used when programming Rolling Code Motorline remote controls or MX13 transmitter.

Remote control programming:

- 1 Press LEARN button once and LED4 will flash once.
- 2 Then press the button you want to program.

Programming transmitter MX13:

- 1 Press LEARN button 2 quick times and **LED4** will flash 2 times.
- 2 Press MX13 PROG button only once.





 To reset the memory, press the **LEARN** button for 10 seconds and all MX13 remote controls and transmitters will be cleared.

· While pressing LEARN button, LED4

At the end of 10 seconds LED4 will flash and turn off confirming the operation.



LEDs

- · LED 1: (ON) Indicates that it is being powered from 230Vac. | OFF - No power supply.
- · LED 2: (ON) Closed SEC Contact | (OFF) Contact "SEC" open (whenever a signal from the MX13 is sent the contact open).
- LED 3: (ON) Closed "STR" Contact | (OFF) Contact "STR" open.
- · LED 4: Programming led.







CONECTORS

• L/N: 230Vac power input. SIG: Pulse input.

R/G/B: Connection of RGB LEDS.

- +/-: External accessory supply (max. 150mA).
- SEC: NC safety signal output.
- STR: Open signal output NO.
- ANT: Antenna plus pole input.
- **↓:** Antenna ground input.



07. PROGRAMMATION

MX13 TRANSMITTER (OPCIONAL)

Wireless transmitter, which allows the connection of obstacle detection kits (safety rubber, magnetic contact, etc.) for communication with MR13.

This device performs automatic function tests with MR13 at defined time intervals, providing longer battery life.



DIPPER

• Dippers 1 and 2 define the time interval for receiving MX13 test signals.

This communication is made to ensure that both devices are working perfectly.



• Dipper 3 has the function of changing the logic of



- The higher the communication level, the shorter the battery life.
- For MX13 and MR13 devices to be synchronized, you must configure dippers 1 and 2 in the same way on both devices.

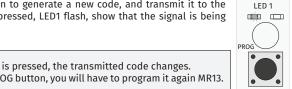






PROG BUTTON AND LED 1

• The PROG button has the function to generate a new code, and transmit it to the receiver. Each time the button is pressed, LED1 flash, show that the signal is being transmitted.





Each time the PROG button is pressed, the transmitted code changes. This way, if you press the PROG button, you will have to program it again MR13.



CONECTOR



• INIB - This input has the function to desactivate the operation of the SAFETY input, through a NO contact for press button or magnetic contact.



• SAFETY - NO or 8K2 input, defined in dipper 3. Whenever this input is triggered an order will be sent to MR13 to open the SEC contact.



