## Dítec



## Ditec ION4-ION6

(translation of the original instructions)

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## 1. General safety precautions <br> 

Please follow these instructions. Failure to observe the information given in this manual may lead to personal injury or damage to the equipment. Keep these instructions for future reference.

This installation manual is intended for qualified personnel only. Installation, electrical connections and adjustments must be performed by qualified personnel, in accordance with Good Working Methods and in compliance with the current regulations. Read the instructions carefully before installing the product.
Bad installation could be dangerous.
This manual and those for any accessories can be downloaded from www.assaabloy.com.

- The packaging materials (plastic, polystyrene, etc.) should not be discarded in the environment or left within reach of children, as they are a potential source of danger.
Before installing the product, make sure it is in perfect condition.
Do not install the product in explosive areas and atmospheres: the presence of inflammable gas or fumes represents a serious safety hazard.
Before installing the motorisation device, make all the necessary structural modifications to create safety clearance and to guard or isolate all the crushing, shearing, trapping and general hazardous areas.
Make sure the existing structure is up to standard in terms of strength and stability. The motorisation device manufacturer is not responsible for failure to observe Good Working Methods when building the frames to be motorised, or for any deformation during use.
The safety devices (photocells, safety edges, emergency stops, etc.) must be installed taking into account: applicable laws and directives, Good Working Methods, installation premises, system operating logic and the forces developed by the motorised door or gate.
The safety devices must protect against crushing, cutting, trapping and general danger areas of the motorised door or gate.
Display the signs required by law to identify hazardous areas.
Each installation must bear a visible indication of the data identifying the motorised door or gate. When necessary, connect the motorised door or gate to an effective earthing system that complies with the current safety standards.

4During installation, maintenance and repair operations, cut off the power supply before opening the cover to access the electrical parts.
The automation protection casing must be removed by qualified personnel only.
A The electronic parts must be handled using earthed antistatic conductive arms. The manufacturer of the motorisation declines all responsibility if component parts not compatible with safe and correct operation are fitted.
Only use original spare parts for repairing or replacing products.
The installer must supply all information concerning the automatic, manual and emergency operation of the motorised door or gate, and must provide the user with the operating instructions. The installer must ensure that the temperature range indicated in the technical specifications is compatible with where the gate will be used.

## General safety precautions for the user

$\triangle$These precautions are an integral and essential part of the product and must be supplied to the user.
Read them carefully since they contain important information on safe installation, use and maintenance.
These instructions must be kept and forwarded to all possible future users of the system.
This product must only be used for the specific purpose for which it was designed.
Any other use is to be considered improper and therefore dangerous. The manufacturer cannot be held responsible for any damage caused by improper, incorrect or unreasonable use.
Avoid operating in the proximity of the hinges or moving mechanical parts. Do not enter within the operating range of the motorised door or gate while it is moving.
Do not obstruct the motion of the motorised door or gate, as this may cause a dangerous situation.
The motorised door or gate may be used by children over the age of 8 and by people with reduced physical, sensorial or mental abilities, or lack of experience or knowledge, as long as they are properly supervised or have been instructed in the safe use of the device and the relative hazards.
Children must be supervised to make sure they do not play with the device, nor play/remain in the sphere of action of the motorised door or gate.
Keep remote controls and/or any other command devices out of the reach of children, to avoid any accidental activation of the motorised door or gate.
In the event of a product fault or malfunction, turn off the power supply switch. Do not attempt to repair or intervene directly, and contact only qualified personnel.
Failure to comply with the above may cause a dangerous situation.
Any repair or technical intervention must be carried out by qualified personnel.
Cleaning and maintenance work must not be carried out by children unless they are supervised.
To ensure that the system works efficiently and correctly, the manufacturer's indications must be complied with and only qualified personnel must perform routine maintenance on the motorised door or gate. In particular, regular checks are recommended in order to verify that the safety devices are operating correctly.
All installation, maintenance and repair work must be documented and
made available to the user.
Only lock and release the door wings when the motor is switched off. Do not enter within the operating range of the wing.
Fi To dispose of electrical and electronic equipment correctly, users must take the product to special "recycling centres" provided by the municipal authorities.

## 2. Declaration of incorporation of partly completed machinery

(Directive 2006/42/EC, Annex II-B)
The manufacturer ASSA ABLOY ES AB, with headquarters in Lodjursgatan 10, SE-261 44 Landskrona, Sweden, declares that the Ditec ION4-ION6 automation for swing gates:

- is designed to be installed on a manual gate to form a machine pursuant to Directive 2006/42/ EC. The manufacturer of the motorised gate must declare conformity with Directive 2006/42/ EC (annex II-A) prior to initial machine start-up;
- complies with the applicable essential safety requirements indicated in Annex I, Chapter 1 of the Directive 2006/42/EC;
- complies with the RED Directive 2014/53/EU;
- the safety functions are compliant with Category 2, PLc according to EN ISO 13849-1;
- the technical documentation complies with Annex VII-B of the Directive 2006/42/EC;
- the technical documentation is managed by the Technical Office of Ditec Spa (with headquarters in Largo U. Boccioni 1 - 21040 Origgio (VA) - ITALY) and is available upon request, sending an e-mail to info@ditecautomations.com ;
- a copy of the technical documentation will be given to competent national authorities, following a suitably justified request.

Landskrona, 26-02-2018


### 2.1 Machinery Directive

Pursuant to Machinery Directive (2006/42/EC) the installer who motorises a door or gate has the same obligations as the manufacturer of machinery and as such must:

- prepare the technical data sheet which must contain the documents indicated in Annex V of the Machinery Directive;
(The technical data sheet must be kept and placed at the disposal of competent national authorities for at least ten years from the date of manufacture of the motorised door or gate);
- draw up the EC Declaration of Conformity in accordance with Annex II-A of the Machinery Directive and deliver it to the customer;
- affix the EC marking on the motorised door or gate, in accordance with point 1.7.3 of Annex I of the Machinery Directive;
- ensure compliance of the motorised door or gate with safety regulations, by installing the necessary safety devices;


## 3. Technical specifications

|  | ION4 | ION4J | ION6 | ION6J |
| :---: | :---: | :---: | :---: | :---: |
| Maximum stroke | 12 m |  |  |  |
| Maximum gate weight | 400 Kg |  | 600 Kg |  |
| Gate speed | 0,1 $\div 0,3 \mathrm{~m} / \mathrm{s}$ |  |  |  |
| Thrust | 200N nominal, 600 N start-up |  | 300N nominal, 800N start-up |  |
| Power supply | $230 \mathrm{~V} \sim 50 / 60 \mathrm{~Hz}$ | $120 \mathrm{~V} \sim 50 / 60 \mathrm{~Hz}$ | $230 \mathrm{~V} \sim 50 / 60 \mathrm{~Hz}$ | $120 \mathrm{~V} \sim 50 / 60 \mathrm{~Hz}$ |
| Power absorption | 0,45A | 0,9A | 0,6A | 1,2A |
| Fuse | T1A | F2A | F1,6A | F3,15A |
| Power | 100 W |  | 130 W |  |
| Intermittence | 80 cycles/day, 30 continuous cycles |  |  |  |
| Lifespan | From 50,000 to 150,000 cycles, depending on the conditions indicated in table (see the product lifespan charts) |  |  |  |
| Acoustic pressure | $L p A \leqslant 70 \mathrm{~dB}(\mathrm{~A})$ |  |  |  |
| IP degree of protection | 44 |  |  |  |
| Usage temperature | $\text { - } 20^{\circ} \mathrm{C}+55^{\circ} \mathrm{C} \text {, }-35^{\circ} \mathrm{C} \text { }+55^{\circ} \mathrm{C} \text { with active } \mathrm{NIO}$ |  |  |  |
| Product size | $300 \times 260 \times 195$ |  |  |  |
| Control panel | LCU48 |  |  |  |
| Motor output | $24 \mathrm{~V}=10 \mathrm{~A}$ max |  |  |  |
| Power supply to accessories | 24V - 0 0,3 max |  |  |  |
| Radio frequency | $433,92 \mathrm{MHz}$ |  |  |  |
| Storable radio codes | 100 / 200 vedi $\mathrm{RO} \rightarrow \mathrm{MU} \rightarrow 20 / 10$ |  |  |  |


| Index of conditioning factors |  |  |  |
| :---: | :---: | :---: | :---: |
|  |  | ION4 | ION6 |
| Gate wing weight | >150Kg | 10 | - |
|  | >200Kg | 20 | 10 |
|  | >300Kg | 30 | 20 |
|  | $>400 \mathrm{Kg}$ | - | 30 |
| Gate wing width | >4m | 20 | 10 |
|  | $>8 \mathrm{~m}$ | - | 20 |
| Wheel diameter < 100 mm |  |  | 0 |
| Saline environment |  |  | 0 |
| Safety edge installed |  |  | 0 |
| R1/R2 > default |  |  | 0 |
| VA/VC > default OC/CB < default |  |  | 0 |

## Example of lifespan calculation for ION4

| Gate wing weight>150Kg | 10 |
| :--- | :--- |
| Gate wing width>4.5m | 10 |
| Dust | 10 |
| Safety edges installed | 10 |
| VA/VC > default | 10 |
| Total stress index | 50 |

Estimated lifespan - 80,000 cycles Estimated daily cycles 22 (for 10 years)


Index of conditioning factors


## 4. Standard installation



| Rif. | Description | Cable |
| :---: | :---: | :---: |
| 1 | Remote control | 1 |
| 2 | Flashing light | $2 \times 1 \mathrm{~mm}^{2}$ |
|  | Antenna (integrated into the flashing light) | coaxial $50 \Omega$ |
| 3 | Key selector switch | $4 \times 0,5 \mathrm{~mm}^{2}$ |
|  | Digital combination wireless keypad | 1 |
| 4 | Photocells | $4 \times 0,5 \mathrm{~mm}^{2}$ |
| 5 | Actuator ION with control panel | $3 \mathrm{G} \times 1,5 \mathrm{~mm}^{2}$ |
| 6 | Safety edge | $2 \times 0,5 \mathrm{~mm}^{2}$ |
| A | Connect the power supply to a type-approved omnipolar switch, with a contact opening distance of at least 3 mm (not supplied). <br> The connection to the mains must follow an independent path, separate from the connections to the control and safety devices. |  |

5. Dimensions

6. Main components


(11)


Descrizione
Motor
Control panel
Key release
Pinion
Cable inlet
13 Power supply terminal and fuse

## 7. Installation

The given operating and performance features can only be guaranteed with the use of DITEC accessories and safety devices.
Unless otherwise specified, all measurements are expressed in mm.

### 7.1 Preliminary checks

Check the stability of the wing (derailing and lateral falls) and the sliding wheels and that the upper guides do not cause any friction.
The sliding guide must be securely fixed to the ground for the full length within doorway and must have no irregularities that could hinder the movement of the wing.
The opening and closing stops must be fitted.
If the gate has slits, make sure they are covered to prevent shearing points or install active safety edges on the columns.
Safety device should be installed at the end of the wing to reduce the collision force.
NB:

- Make sure that the gate can not exit the sliding guides and fall.
- Make sure that the protection system and any manual release function correctly.


### 7.2 Base plate position

Make a concrete base with the anchor ties and base plate embedded, which must be level and clean and of the size indicated in the figure.



- Release the gearmotor [1] (see OPERATING INSTRUCTIONS). Loosen the front screw [2] and remove the casing by pressing on its sides [3-4].
- Place the gearmotor on the base plate.
- Adjust the gearmotor horizontally by sliding italong the slots of the gearmotor base and vertically with four levelling screws [A].
NB: during the vertical adjustment, keep the gearmotor slightly raised from the base plate so that the rack can be fixed and subsequent adjustments are possible.
- After adjusting, fix the gearmotor using screws [B].


### 7.4 Rack installation



- Release the gearmotor (see OPERATING INSTRUCTIONS) and open the gate.
- Place the rack against the pinion and sliding the gate manually fix it along its whole length.

NB: To make it easier to align the rods correctly, use a scrap piece of rack and rest it underneath the junction point, as shown in the figure detail.

- Once fixed, vertically adjust the gearmotor to give a play of about 2 to 3 mm between the pinion and the rack.
- Secure the gearmotor with the [B] screws using a tightening torque of 20-25 Nm.
- Slightly lubricate the rack and pinion after assembly. Manually check that the gate slides evenly and without friction.


### 7.5 Operation with virtual encoder

ION4-ION6 gearmotors do not require limit switches because they have a virtual encoder.
Mechanical opening and closing end stops must be installed.
The gate automatically slows when approaching the end stops.
WARNING: when the gate reaches the opening or closing limit stop, it reverses briefly to facilitate manual release of the gearmotor.

### 7.6 Installation of optional accessories

### 7.6.1 Magnetic limit switches

 mechanical stops.With a limit switch installed, slowdown is carried out at regulated power to overcome possible friction.

For the installation of the limit switch kit, refer to the NES100FCM manual.
To position the limit switches, you can use the menu $\overline{5} F \rightarrow$ TF lvisible by activating the additional configurations AT $\rightarrow$ RA).
The display shows the status of the limit switches:

- FR: opening limit switch configured and activated;
- F [: closing limit switch configured and activated;
- N.U. (both parts of display active): opening limit switch not configured and activated;
- $N \mathbb{N}$ (no part of display active): closing limit switch not configured and activated;
- $\square$ (central part of display active): no limit switch activated;

With the limit switches configured as STOP (FA = SX; FC = SX) the anti-violation function is activated. When the automation stopped open or closed, if the gate backs off releasing the limit switch, it is brought back into position avoiding openings from external forces [energy saving must be disabled ES = OFF].

### 7.6.2 Battery kit

For installation of the battery kit, refer to the SBU-IONSBU-BBU20-BBU65 (IP2254) manual.

> The battery kit guarantees operation if there is a power cut. For advanced control of battery-powered operation, refer to the EM menu.

### 7.6. 3 Remote release handle

For installation of the remote release handle, refer to the IONSBM and ASR2 manual.

A microswitch guarantees safety.
When the handle is released, the control panel performs a reset

## 8. Electrical connections



$\triangle$Before connecting the power supply, make sure the plate data correspond to that of the mains power supply.
An omnipolar disconnection switch with a contact opening distance of at least 3 mm must be fitted on the mains supply.
Check there is an adequate residual current circuit breaker and overcurrent cutout upstream of the electrical system.
For the power supply, use a H05RN-F 3G1.5 type electric cable. Connect it to terminals L (brown), N (blue), $\underset{\theta}{( })$ (yellow/green) inside the automation.
NOTE: the maximum permisible section of the wire is AWG14 ( $2 \mathrm{~mm}^{2}$ ).
In order to comply with essential requirements of standards in force, reclose the cover once the wires have been connected to the terminal.
In the external automation section, the connections to the mains power supply and any other low voltage wires ( 230 V ) must be made on an independent channel separated from the connections to the command and safety devices (SELV = Safety Extra Low Voltage).
The channel must penetrate the automation through the holes on the base plate by a few centimetres.
Make sure there are no sharp edges that may damage the power supply cable.
Make sure the mains power wires (230V) and the accessory wires (24V) are separated. The cables must be double insulated. Unsheathe them in line with the relative connection terminals, and use cable fasteners (see ref. A) or straps (not supplied by us) to hold them in place.


## 10. Using of the menus

NB: pressure on the keys may be quick (less than 2 s ) or prolonged (longer than 2 s ). Unless specified otherwise, quick pressure is intended.
To confirm the setting of a parameter, prolonged pressing is necessary.

### 10.1 Switching the display ON and OFF

The procedure to switch on the display is as follows:

- press the ENTER key ENTER
- the display functioning check starts


The procedure to switch off the display is as follows:
- press the ESC key

NB: there is no automatic exit from the WZ quick configuration menu. For all the other menus, the display switches off automatically after 60 seconds of inactivity.

### 10.2 Navigation keys

- The simultaneous pressing of the $\uparrow$ and ENTER keys produces an opening command.

- The simultaneous pressing of the $\downarrow$ and ENTER keys produces a closing command.

- The simultaneous pressing of the $\uparrow$ and $\downarrow$ keys produces a POWER RESET command (power supply interruption and automation restart).

- Keep the UP $\uparrow$ or DOWN $\downarrow$ key pressed to begin fast menu scrolling.

To set a parameter, select the desired value and press ENTER for 2 seconds to save.
Example: setting of 30 seconds for parameter TC


- In some menus, the parameter measurement unit can be viewed by pressing the ENTER key once the value has been displayed.

|  |  |  |
| :---: | :---: | :---: |



## 11. Product start-up

For rapid configuration of the product, use the WIZARD (WZ) menu or the second level AT (Automatic Configurations) menu [See par. 15.2].
For detailed, customised configuration, use the main menus $B C, B A, R O, S F, C C, E M, A P$.

### 11.1 WZ configuration wizard menu

## To access the WZ configuration wizard menu:

Hold down the ENTER button for 2 seconds.
When OK has stopped flashing, DM, the first menu parameter, is displayed.
WI In for 2 sec . DK DM

## To set a parameter:

1. Press ENTER to access the configuration items.
2. Scroll UP/DOWN the possible options.
3. To confirm, press the ENTER button for 2 seconds. The selected value flashes and when it has finished, the next parameter appears.

## IMM只T for 2 sec (RT [5

Display
(default)
( ME: $20 \mathrm{~cm} / \mathrm{s}$

- Por other options, see the specific menu.


## To save the configuration:

In the CO parameter select YS (yes) and press the ENTER button for 2 seconds.
When the configuration has been saved, a power reset is automatically performed on the card.


## To quit without saving changes:

In the CO parameter select NO and press the ENTER button for 2 seconds.

## [D ND For 2 sec . ND

Or: from any main parameter, press the ESC button for 2 seconds.
Example
IIM MESC Hor 2 sec
NOTES

- The set values are only stored on the card if they are saved using the CO parameter.
- The CO parameter and YS/NO options flash constantly.
- When a configuration item is confirmed, it automatically moves on to the next parameter.
- You can scroll through the menu parameters using the UP/DOWN buttons.
- There is no automatic timeout function to quit.


## 12．Commands

i
You are advised to read paragraph 15 for all the details about the possible adjustments．

WARNING：terminal 30 （common positive for commands）has the same functions as terminal 1，so the commands visualised on the display are indicated with 1－5，1－3，etc．
It is different from terminal 1，however，because of the maximum current that can be dispensed and it is also active when the control panel is in standby $E \Sigma \rightarrow \square \mathrm{~N}$ ．

| Command |  | Function | Description |
| :---: | :---: | :---: | :---: |
| $30-5$ | NO | STEP－BY－STEP | When selecting $B[\rightarrow[5 \rightarrow \mid-5$ ，the closure of the contact ac－ tivates a sequential opening or closing operation：opening－stop－ closing－opening． <br> WARNING：if automatic closure is enabled，the duration of the stop can be defined by selecting $B[\rightarrow \overline{5} 5$ ． <br> The＂opening－stop－closing－opening＂sequence can be changed to＂opening－stop－closing－stop－opening＂by selecting $B[\rightarrow P P$ ． |
|  |  | OPENING | When selecting $][\rightarrow[5 \rightarrow \mid-]$ ，the closure of the contact ac－ tivates an opening operation． |
| 1 － 6 | NO | CLOSURE | When selecting $B[\square \square \rightarrow \mid-4$ ，closing the contact activates a closing operation． |
| $\pm 6$ | NC | SAFETY STOP | When selecting $B[\rightarrow \square 4 \rightarrow \mid-6$ ．opening of the safety contact stops and prevents any movement． <br> NB：to set different safety contact functions，see the RP $\rightarrow$ 丂 $M$ parameter settings． |
| － 8 | NC | CLOSING <br> SAFETY <br> DEVICE | The opening of the safety contact triggers a reversal of the movement（reopening）during the closing operation． <br> When selecting $B[\rightarrow \bar{J} \square \rightarrow \square N$ ，the opening of the contact pre－ vents any operation when the automation is idle． <br> When selecting $B[\rightarrow \bar{J} \square \rightarrow \square F$ ，the opening of the contact only prevents closure when the automation is idle． |
|  | NC | CLOSING／ OPENING SAFETY DEVICE | The opening of the safety contact stops and prevents any move－ ment． <br> NB：operation corresponds to that of contact $1-6$ with AP $\rightarrow$ 5M $\rightarrow$ 日 5 ． |
| $1-20$ | NO | PARTIAL OPENING | The closure of the contact activates a partial opening operation． Once the automation stops，the partial opening control performs the opposite operation to the one performed before the stop． |
| $1 \longrightarrow 20$ | NC | AUTOMATIC CLOSURE OR STOP | Selecting AP $\rightarrow$ 己ロ $\rightarrow$ I－ ，the permanent closure of the contact enables automatic closure if $A[\rightarrow 1-ट$ ． <br> Selecting AP $\rightarrow$ 己 $\square \rightarrow 1$－ 9 ，the opening of the safety contact causes the movement to stop． <br> NB：the flashing light flashes． |

WARNING：make a jumper for all NC contacts if not used，or deactivate them via the relative menu． Terminals with the same number are equal．

## 12．1 SOFA1－SOFA2 or GOPAVRS self－controlled safety edge

| Command |  | Function | Description |
| :---: | :---: | :---: | :---: |
| $\begin{aligned} & \text { SOFA1-SOFA2 } \\ & \text { GOPAV } \\ & \hline \end{aligned}$ |  | SAFETY TEST | Insert the SOFA1－SOFA2 or GOPAVRS device in the slot for plug－in boards AUX1 or AUX2． <br> If the test fails，an alarm message appears on the display． |
| $10 \circ$ |  |  |  |
| －6 | NC | SAFETY STOP | When selecting RP $\rightarrow$ DE $\rightarrow 541$ ，connect the output contact of the safety device to terminals 1－6 on the con－ trol panel lin series with the photocell output contact， if installed）． |
| L 8 | NC | CLOSURE SAFETY DEVICE | When selecting RP $\rightarrow$ 卫日 $\rightarrow \overline{5} 41$ ，connect the output contact of the safety device to terminals 1－8 on the con－ trol panel lin series with the photocell output contact， if installed）． |
|  | NC | CLOSING／ OPENING SAFETY DEVICE | When selecting $\mathrm{AP} \rightarrow$ Б日 $\rightarrow \overline{5} 41$ ，connect the output contact of the safety device to terminals 1－6－8 on the control panel lin series with the photocell output con－ tact，if installed）． <br>  |

## 13．Outputs and accessories

| Output | Value of <br> accessories | Description |
| :--- | :--- | :--- |


| Output | Value of accessories | Description |
| :---: | :---: | :---: |
|  | 6ZENRS ZENPRS | The control panel is fitted with a housing for modules of the 6ZENRS radio receiver type ( 433.92 MHz ). <br> Can be replaced with a module of the ZENPRS radio receiver type 1868.35 MHz ). <br> When using slot-in radio boards, remove the RDX module. The display will show Rl'. <br> WARNING: the modules must be inserted and removed with the power supply disconnected. |
|  | BIXM R2 | COM - This allows the functioning configurations to be saved using the <br>  <br> The saved configurations can be recalled using the function $\bar{\zeta} F \rightarrow R[$. <br> COM - The storage module allows the remote controls to be stored. If the control panel is replaced, the storage module being used can be inserted in the new control panel. <br> WARNING: the storage module must be inserted and removed with the power supply disconnected, and paying attention to the positioning direction. |
| $\begin{aligned} & \text { BAT } \\ & \begin{array}{\|l\|l\|} \hline: & \square \\ \hline \square & \square \\ \hline \end{array} \end{aligned}$ | SBU | BAT - Battery-powered operation. <br> The batteries are kept charged when the power supply is on. If the power supply is off, the panel is powered by the batteries until the power is reestablish or until the battery voltage drops below the safety threshold. The control panel turns off in the last case. WARNING: the batteries must always be connected to the control panel for charging. Periodically check the efficiency of the batteries. <br> NB: the operating temperature of the rechargeable batteries is from $+5^{\circ} \mathrm{C}$ to $+40^{\circ} \mathrm{C}$. <br> For advanced control of battery-powered operation, refer to the menu E M. |

## 14. Jumper setting

| Jumper | Description | OFF | ON |
| :---: | :--- | :--- | :--- |
| JR1 | Display mode selection. | Display mode. <br> Only the values and pa- <br> rameters present can be <br> displayed. | Maintenance mode. <br> Only the values and pa- <br> rameters present can be <br> displayed and modified. |
| Activated maintenance |  |  |  |
| mode is indicated by the |  |  |  |
| permanent switching on of |  |  |  |
| the right-hand point on the |  |  |  |
| display. |  |  |  |


| Jumper | Description | 1 | 10 |
| :---: | :---: | :---: | :---: |
| JR5 | Selection of power supply - auxil- <br> iary board. | AUX1 <br> powered from 0-1. <br> (default) | AUX1 powered from 0-30. |

## 15. Adjustments

NB: depending on the type of automation and control panel, some menus may not be available.

### 15.1 Main menu

| Display | Description |
| :---: | :---: |
| $\begin{array}{ll} 11 \\ V N \end{array}$ | WZ - Wizard <br> Quick configuration menu |
|  | AT - Automatic Configurations. <br> The menu allows you to manage the automatic configurations of the control panel. |
|  | BC - Basic Configurations. <br> The menu allows you to display and modify the main settings of the control panel. |
|  | BA - Basic Adjustments. <br> The menu allows you to display and modify the main adjustments of the control panel. NB: some settings require at least three operations before they are set correctly. |
|  | RO - Radio Operations. <br> The menu is used to manage the radio functions of the control panel lalarm management, diagnostics enabling, FW updating). |
| $-1$ | SF - Special Functions. <br> The menu allows you to set the password and manage the special functions in the control panel. |
|  | CC - Cycles Counter. <br> The menu allows you to display the number of operations carried out by the automation and manage the maintenance interventions. |
| EMA | EM - Energy Management. <br> The menu allows you to display and modify the energy saving settings and adjustments (Green Mode and battery management). |
|  | AP - Advanced Parameters. <br> The menu allows you to display and modify the advanced settings and adjustments of the control panel (limit switch mode, selection of devices connected to the terminals, disengagement duration adjustments, flashing light adjustments, etc.). <br> NB: some settings require at least three operations before they are set correctly. |

From the main menu you can access the second level menu as follows:

- use the $\sqrt{\square}$ and $\sqrt{\square}$ keys to select the required function
- press ENTER to confirm

After confirming the selection, you access the second level menu.
For each function of the main menu, there are also additional configurations that can be viewed by enabling the $\wp$ function (see the following paragraph).

NB: to check if the parameters have actually been modified, quit the relative parameter and then access it again.
The modifications will take effect from the next operation.

### 15.2 Second level menu - AT (Automatic Configurations)

DM - Direction mode
RT-opens to the right
LF-open to the left

### 15.3 Second level menu - BC (Basic Configurations)



15．3．1 Additional BC level parameters that can be configured （available with 月T $\rightarrow$ 月月 enabled）

|  | Display | Description | Selec avail | tions able |
| :---: | :---: | :---: | :---: | :---: |
|  |  | HR－Enabling of＂operator present＂function <br> ON－Enabled <br> OF－Disabled <br> NB：Set $H P \rightarrow \square N$ only if $54 \rightarrow 1$－ 4 and $[5 \rightarrow 1$－$]$ ． <br> WARNING： <br> －If the OPERATOR PRESENT function is activated，make sure that no－ one is near the automation when an opening or closing command is given． <br> －The actuation device for the OPERATOR PRESENT function must be placed within the visibility of the guided part but away from the moving parts． <br> It must also be installed at a minimum height of 1.5 m and be placed out of the public＇s reach． | MiN |  |
| （ | $15$ | C5－Operation of command associated with contact 30－5 <br> 1－5－Step－by－step <br> 1－3－Opening |  | $1-3$ |
| $\bigcirc$ | $[1$ | 64 －Functioning of safety stop／closing command． <br> 1－4－Closing <br> 1－6－Safety stop | $1-1.1$ | $1-\infty$ |
|  | Fin | RM－Radio receiver operation <br> 1－5－Step－by－step <br> 1－3－Opening | $1-5$ |  |
|  | $-111$ | AM－Operation of AUX1 plug－in control board <br> 1－5－Step－by－step <br> 1－3－Opening |  |  |
|  |  | MP－Start－up at maximum power <br> ON－During start－up it increases the thrust on obstacles to maximum OFF－During start－up，the thrust on obstacles is the one adjusted by R 1 －R 己． |  |  |
|  |  | PP－Setting step－by－step sequence from command 1－5． <br> ON－Opening－Stop－Closing－Stop－Opening <br> OF－Opening－Stop－Closing－Opening | MiN |  |
|  |  | S5－Duration of STOP in step－by－step sequence from command 1－5． <br> ON－Permanent <br> OF－Temporary |  |  |

### 15.4 Second level menu - BA (Basic Adjustment)

Description
It is set with different intervals of sensitivity.

- from $0^{\prime \prime}$ to $59^{\prime \prime}$ with intervals of 1 second
- from $1^{\prime}$ to $2^{\prime}$ with intervals of 10 seconds


## R2－Adjustment of thrust on obstacles and motor current during

 closure．［\％］The control panel is fitted with a safety device which，when it detects an obstacle：
－reverses the movement during closure operations outside the limit area for detecting obstacles；
－stops the movement during closure operations within the limit area for detecting obstacles．
The obstacle detection area during closure is determined by the type of limit switch installed．If there is no limit switch，it is determined according to the selection $B R \rightarrow \square[$ ．
00 －Minimum thrust
99 －Maximum thrust


50

## 15．4．1 Additional BA level parameters that can be configured （available with $口 T \rightarrow$ 月月 enabled）

|  | Display | Description | Selections available |
| :---: | :---: | :---: | :---: |
|  | $\prod 1$ | DT－Adjustment of obstacle recognition time［s／100］ <br> 10 －Minimum <br> 60 －Maximum <br> NB：the parameter is adjusted in hundredths of a second． |  |
|  | $\square T$ | ST－Adjustment of start time［s］ <br> 0.5 －Minimum <br> 3.0 －Maximum |  |
| $\frac{1}{\infty}$ |  | TA－Adjustment of acceleration time during opening［s］ <br> 0.5 －Minimum <br> 9．9－Maximum |  |
|  |  | TQ－Adjustment of acceleration time during closure［s］ <br> 0.5 －Minimum <br> 9．9－Maximum |  |
|  | $\begin{array}{lll} 1 & M & 1 \\ V & 1 \end{array}$ | VM－Initial movement speed［cm／s］ <br> 00 －Minimum <br> 15 －Maximum |  |
|  | $1 \pi$ | TD－Adjustment of deceleration time during opening［\％］ Regulates the slope of the deceleration ramp during opening． <br> 10 －Minimum <br> 99 －Maximum |  |
|  | $111$ | TU－Adjustment of deceleration time during closure［\％］ <br> Regulates the slope of the deceleration ramp during opening． <br> 10 －Minimum <br> 99 －Maximum |  |
|  |  | $O B$－Adjustment of deceleration distance during opening．［cm］ Indicates the distance from the end of the opening stroke for the start of the deceleration ramp． <br> 05 －Minimum <br> 99 －Maximum |  |

Description
OB - Adjustment of deceleration distance during closing. [cm]
Indicates the distance from the end of the closure stroke for the
start of the deceleration ramp.
05 - Minimum
$99-$ Maximum
PO - Adjustment of approach speed during opening [cm/s]
Indicates the speed from the end of the deceleration ramp to the
end of the opening stroke
03 - Minimum
$10-$ Maximum
NB: gradually increase the approach speed if there is a series of
quick vibrations lchattering) in heavy gates installed with a slight
incline.

NB: make adjustments gradually and only after performing at least three complete operations to allow the control panel to be set correctly and detect any friction during operations.

### 15.5 Second level menu - RO (Radio Operations)



WARNING: selecting MU $\rightarrow$ 20 (200 remote controls), the configurations $U 1$ and $U$ 己 saved with the $\zeta F \rightarrow \bar{L} b^{\prime}$ command will be lost. This also applies for the last configuration reloaded with RL. In addition, new configurations cannot be saved on $\cup 1$ and $\cup 己$.

|  | Display | Description ${ }_{\text {a }}$ ( ${ }_{\text {Select }}$ availa |
| :---: | :---: | :---: |
| $\begin{aligned} & 0 \\ & 0 \\ & 0 \\ & \hline 0 \\ & \hline 0 \\ & 0 \\ & 0 \\ & 1 \\ & 0 \\ & 0 \\ & 0 \end{aligned}$ |  | RK - Menu navigation using remote control keyboard <br> ON - Enabled <br> OF - Disabled <br> With the display turned off, quickly type in the sequence of keys (3) (3) (2) (1) from the stored remote control you want to use. <br> Make sure all the CH keys are stored. <br> WARNING: during navigation with a remote control keyboard ALL the stored remote controls are inactive. <br> To make viewing and adjustment easier lavoiding the need to continuously press the remote controll, press the UP $\uparrow$ or DOWN $\downarrow$ key once to begin slowly scrolling through the parameters. <br> This scrolling movement is faster if the UP $\uparrow$ or DOWN $\downarrow$ key is pressed twice. To stop the scrolling, press ENTER. <br> To confirm your choice of parameter, press ENTER again. <br> To test any new setting, switch off the display and issue an opening command using key (3). <br> Navigation using a remote control keyboard is automatically disabled after 4 minutes of inactivity or by setting $R K \rightarrow \square F$. |

### 15.5.1 Additional RO level parameters that can be configured (available with 月 $^{\text {T }} \rightarrow$ ПП enabled)



15.6 Second level menu - SF (Special Functions)


## Description

## RL - Loading of last configuration set <br> 

The control panel automatically saves the last configuration set, and keeps it memorised in the storage module.
In the event of a fault or the replacement of the control panel, the last configuration of the automation can be restored by inserting the storage module and loading the last configuration set.

### 15.6.1 Additional SF level parameters that can be configured (available with $Я T \rightarrow$ ЯЯ enabled)



|  | Display | Description |
| :---: | :---: | :---: |
| $\frac{1}{4}$ |  | AR - Alarm reset <br> Resets all the alarms in the memory (counters and log). <br> (1)2" <br> NB: when the installation has been completed, you are advised to delete the alarms in order to facilitate future checks. |
|  | $\begin{aligned} & 1111 \\ & 11 \end{aligned}$ | IM - Motor current visualisation |
|  | $1 T$ | TT - Display min / max temperatures recorded <br> - by pressing for 2 seconds the values are reset <br> - minimum value with active right point |
|  | $11$ | TF - Limit switch test <br> Only FA / FC are displayed when the respective limit switches are configured and active. If the limit switches are active but not configured: <br> - FA = N.O. (both active points) <br> - FC = NO (no active point) |
|  |  | UP - Firmware update Activates the card bootloader in order to update the firmware. <br> (1)2" |

### 15.7 Second level menu - CC (Cycles Counter)

Display

### 15.7.1 Additional CC level parameters that can be configured (available with 月 $^{\text {T }} \rightarrow$ ค月 enabled)

|  | Display | Description ${ }_{\text {S }}$ | Selections available |
| :---: | :---: | :---: | :---: |
| $0$ | $[F$ | CA - Setting the maintenance alarm <br> (factory setting - alarm deactivated: 0.000 .00 ). <br> You can set the required number of operations (regarding the partial operation for signalling the maintenance alarm. <br> When the set number of operations is reached, the alarm message appears display $b^{\prime} \square$. <br> Example: <br> Setting the maintenance alarm after 700 operations (00) (07) (00) | ons counter) ears on the |
|  |  | OA - Selecting maintenance alarm display mode <br> 00 - Visualisation on display (alarm message $l^{\prime}$ ( ${ }^{4}$ ) <br> 01 - Visualisation on flashing light (with the automation idle, 4 flashes are made and then repeated every hour) and on display (alarm message l' [7). <br> 02 - Visualisation on "open gate" indicator light (with the automation closed, 4 flashes are made and then repeated every hour) and on display (alarm message l' ${ }^{\prime}$ ). |  |
|  | 1 | ZP - Reset of partial operations counter $\frac{\sqrt{\text { EIBR }}}{\text { O2" }} \rightarrow \square$ <br> For correct functioning, you are advised to reset the partial operations counte - after maintenance work; <br> - after setting the maintenance alarm interval. | ter: |

### 15.8 Second level menu - EM (Energy Management)

Display

|  | Display | Description | Selections available |
| :---: | :---: | :---: | :---: |
| $\frac{\Sigma}{I I}$ |  | LB－Indication that batteries are almost flat <br> 00 －Visualisation on display（alarm message B［ <br> 01 －Visualisation on flashing light（with the automation idle， 2 flashes are made and then repeated every hour）and on display（alarm message B 可） <br> 02 －Visualisation on＂open gate＂indicator light（with the automation closed， 2 flashes are made and then repeated every hour）and on display （alarm message B（T） |  |

## 15．8．1 Additional EM level parameters that can be configured lavailable with ค $T \rightarrow$ 月月 enabled）

Display

| LL－Voltage threshold for indicating that batteries are almost |
| :--- |
| flat（V） |
| $17-$ Minimum |
| 24 －Maximum |
| NB：it is set with an interval of sensitivity of 0.5 V shown when the |
| decimal point on the right lights up． |


| BT－Battery mode |
| :--- |
| 00 －Anti－panic lperforms the opening operation following a mains supply fail－ |
| ure．The automation opens but does not accept any other commands until |
| the mains supply has been restored）． |
| 01 －Continuous operation－the last operation performed before control panel |
| switch－off will be an opening． |
| 02 －Continuous operation－the last operation performed before control panel |
| switch－off will be an closure． |

## 15．9 Second level menu－AP（Advanced Parameters）

Display

|  | Display | Description | Selections available |
| :---: | :---: | :---: | :---: |
|  |  | D6 - Selection of device connected to terminals 1-6 <br> NO - None <br> PH - Photocells <br> P41 - Photocells with safety test <br> SE - Safety edge lif contact $1-6$ opens, there is a disengagement of 10 cm after the stop) <br> S41 - Safety edge with safety test lif contact 1-6 opens, after the stop there is a disengagement of a duration depending on the selection AP $\rightarrow$ DE |  |
|  |  | D8 - Selection of device connected to terminals 1-8 <br> NO - None <br> PH - Photocells <br> P41 - Photocells with safety test <br> SE - Safety edge <br> S41-Safety edge with safety test | $\begin{array}{llll} M & \square & \square \\ i v & -1 & 1 \\ \square & 11 & - & - \\ 1 & 11 \end{array}$ |
|  |  | R9 - Enabling automatic closing after command 1-9 (STOP). <br> ON - Enabled <br> OF - Disabled <br> When enabled (ON), after a command 1-9, the automation carries out automatic closing lif enabled), after the set time. |  |
|  |  | 68 - Selection of the device simultaneously connected to terminals 1-6 and 1-8 <br> NO - None <br> SE - Safety edge <br> S41-Safety edge with safety test <br> If different from NO, the simultaneous opening of inputs 1-6 and 1-8 causes: <br> - movement stop and reversal during a closing operation <br> - movement stop and disengagement of a duration depending on the selection $A P \rightarrow D E$ during an opening operation |  |
|  |  | DS - Setting of display visualisation mode <br> 00 - No visualisation <br> 01 - Commands and safety devices with radio test <br> Display of countdown to automatic closure. <br> 02 - Automation status <br> 03 - Commands and safety devices <br> NB: the setting $\begin{aligned} & 1 \\ & \}\end{aligned}$ allows you to see when a radio transmission is received, for range checks. |  | NB: make adjustments gradually and only after performing at least three complete operations to allow the control panel to be set correctly and detect any friction during operations.

15.9.1 Additional AP level parameters that can be configured lavailable with $\cap T \rightarrow$ 月月 enabled)

|  | Display | Description | Selections available |
| :---: | :---: | :---: | :---: |
|  |  | 20 - Partial opening command of terminal 1-20 <br> P3 - Partial opening command <br> 1-2 - Enabling of automatic closure <br> 1-9 - Stop input |  |
|  |  | LU - Setting the courtesy light switch-on time (s) <br> To enable the parameter, set the selection BR $\rightarrow$ F F as "courtesy light". <br> It is set with different intervals of sensitivity. <br> NO - Disabled <br> - from 01" to $59^{\prime \prime}$ with intervals of 1 second <br> - from $1^{\prime}$ to $2^{\prime}$ with intervals of 10 seconds <br> - from 2' to $3^{\prime}$ with intervals of 1 minute <br> ON - Permanently enabled (switched off via remote control) <br> NB: the courtesy light switches on at the start of each operation. |  |
| $\frac{0}{4}$ |  | LG - Switch-on time for independently commanded courtesy light [s] <br> To enable the parameter, set the selection BR $\rightarrow$ F F as "courtesy light". <br> It is set with different intervals of sensitivity. <br> NO - Disabled <br> - from 01" to $59^{\prime \prime}$ with intervals of 1 second <br> - from $1^{\prime}$ to $2^{\prime}$ with intervals of 10 seconds <br> - from 2' to $3^{\prime}$ with intervals of 1 minute <br> ON - Switched on and off with remote control <br> NB: the switching on of the light does not depend on the start of an operation, but can be commanded separately using the special remote control key. | $\begin{array}{lll} \square 1 & 1 & - \\ 11 & 1 & - \\ 1 & 1 & -1 \\ 1 & 1 & - \\ 1 & 1 & \square \end{array}$ Miv |
|  | $\square 1$ | PT - Fixed partial opening <br> ON - Enabled <br> OF - Disabled <br> If ON, a partial opening command given on the partial opening position is ignored. <br> With contact 1-20 closed (for example with the timer or manual selector), the gate will partially open. If it is then fully opened (command 1-3) and reclosed (even with automatic closure), it will stop at the partial opening position. |  |
|  |  | DE - Disengagement setting if an edge is triggered [cm] <br> Regulates the disengagement distance when an edge lactive or passive) is triggered during opening or closure. <br> 00 - Deactivated <br> 20 - Maximum |  |
|  |  | DO - Setting of disengagement on stop during opening [mm] <br> Regulates the distance of the disengagement on the mechanical opening stop. <br> 00 - Disabled <br> 15 - Maximum <br> NB: not active if $F$ R $\rightarrow 5 \%$ |  |

Description
DC - Setting of disengagement on stop during closure [mm]
Regulates the distance of the disengagement on the mechanical open-
ing stop.
90- - Masabled
NB: not active if $F[\rightarrow \bar{\circ}$
Adjustment of the lead time for the switch-on of the flashing light,
in relation to the start of the opening operation from a voluntary
command.
00 - Minimum
05 - Maximum
WC - Setting of pre-flashing time on closing [s]
Adjustment of the lead time for the switch-on of the flashing light,
relation to the start of the closing operation from a voluntary com
mand.
00 - Minimum
05 - Maximum

## 16. Signals visualised on the display

 NB: depending on the type of automation and control panel, certain visualisations may not be available.
### 16.1 Display of automation status



NB: the automation status display mode is only visible with Display visualisation mode set to 02.


| Display | Automation closed |
| :--- | :--- | :--- |
| 1 | Automation closed Release door open |
| 1 | Automation open |
| 1 | Automation open Release door open |


| 1 | Automation stopped in intermediate position |
| :---: | :---: |
| L | Automation stopped in intermediate position Release door open |
| N $V$ | Automation closing |
| $\hat{1}$ | Automation that slows down during closing. |
| V11 | Automation opening |
| V | Automation that slows down during opening. |


|  | Automation closed |
| :--- | :--- | :--- |

### 16.2 Display of safety devices and commands

NB: the safety device and command display mode is only visible with Display visualisation mode set at 01 or 03 .

Description

### 16.3 Visualisation of alarms and faults

WARNING: the visualisation of alarms and faults is possible with any visualisation selection. The signalling of alarm messages takes priority over all other displays.

| Type of | Check the mechanical parts. |
| :--- | :--- | :--- |
| alarm | Check connection of motor. |

Thpe of
Type of
alarm

## 17．Troubleshooting

| Problem | Possible cause | Alarm signalling | Operation |
| :---: | :---: | :---: | :---: |
| The control panel does not switch on | No power supply． |  | Check the power supply cable and the relative wiring |
| The automation does not open or close． | No power． |  | Check power supply cable． |
|  | Short circuited accessories | 15 | Disconnect all accessories from termi－ nals $0-1$ la voltage of $24 \mathrm{~V}=$ must be pre－ sent）and reconnect them one at a time． Contact Technical Service |
|  | Blown line fuse． |  | Replace fuse． |
|  | Safety contacts are open． | $\begin{array}{ll} 1-6 & 1-8 \\ 58 \end{array}$ | Check that the safety contacts are closed correctly（NC）． |
|  | Safety contacts not correctly connected or self－controlled safety edge not functioning correctly． | R $1-6$ <br> $R$ 1 <br> $1-8$  <br> R 3 $5 日$ | Check connections to terminals 6－8 on control panel and connections to the self－controlled safety edge． |
|  | Photocells activated． | $1-6 \quad 1-8$ | Check that the photocells are clean and operating correctly． |
|  | The automatic closure does not work． |  | Issue any command．If the problem per－ sists，contact Technical Service |
|  | Motor fault | MB $194$ | Check motor connection，if the problem persists，contact Technical Service． |
|  | Mechanical fault | ｜M3 <br> ｜MG｜ | Check the rack and transmission chain， and／or the mechanical parts． |
|  | Release microswitch open | 亏W | Check that the hatch is closed correctly and the microswitch makes contact． |
|  | Faulty control panel | $I 马$ $I E$ <br> $I B$ $I M$ <br> $I B$ $I$ <br> $I B$ $I$ <br> $I B$ $I R$ | Contact Technical Service |
|  | Both limit switches are active． | $\begin{aligned} & F R . \\ & F[. \end{aligned}$ | Check the connection of the limit switches． |
| The external safety devices are not ac－ tivated． | Incorrect connections be－ tween the photocells and the control panel． |  | Check that $1-6 / 1-日$ is displayed Connect NC safety contacts together in series and remove any jumpers on the control panel terminal board． |
|  |  |  | Check the setting of RP $\rightarrow$ IG and AP $\rightarrow$ 卫日． |
| The automation opens／closes briefly and then stops． | There is a presence of friction． | $\begin{aligned} & \text { MI } \\ & M 19 \\ & \text { IL } \end{aligned}$ | Manually check that the automation moves freely and check the R $1 / R_{\mathrm{R}}$ 己 adjustment Contact Technical Service |


| Problem | Possible cause | Alarm <br> signalling | Operation |
| :--- | :--- | :--- | :--- | :--- |
| The remote control <br> has limited range <br> and does not work <br> with the auto- <br> mation moving. | The radio transmission is im- <br> peded by metal structures and <br> reinforced concrete walls. |  | Replace the transmitter batteries. |

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